



IPE-409 CAD/CAM



Chapter-2

Defining the model

Introduction

❖ Models of **form** and models of **structure**

- Drawing of components and their arrangement in assemblies. Mechanical drawing of a part
- Diagram to show components of a system and how they are connected. Electronic circuit, chemical process etc.

Establishing design representation

Representation of form using drawing

- Representing 3D forms in 2D space by means of engineering drawing on paper or display
- Projecting views in mutually perpendicular planes
- Now 3D forms are represented in 2D by mapping points on the object in multiple mutually perpendicular planes
- Different line style meaning; Sectional view
- Third angle projection; First angle projection
- Pictorial projection; Parallel projection; Perspective projection

Establishing design representation

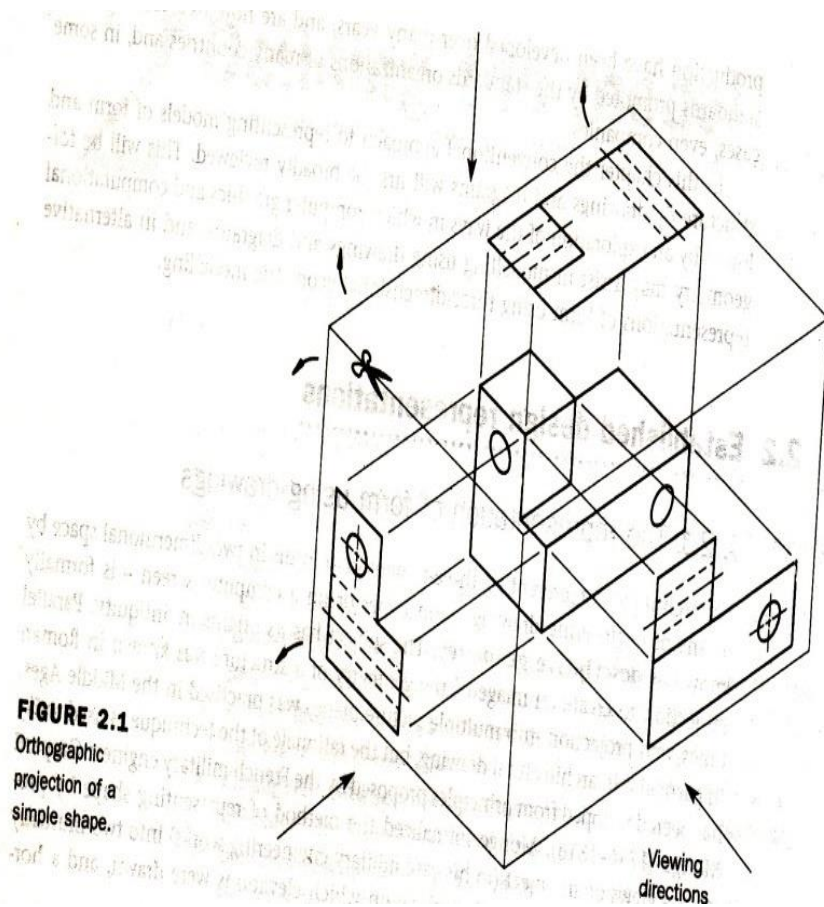


FIGURE 2.2
Parallel pictorial
projection of a
simple shape.

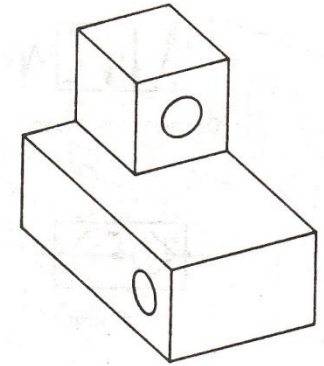
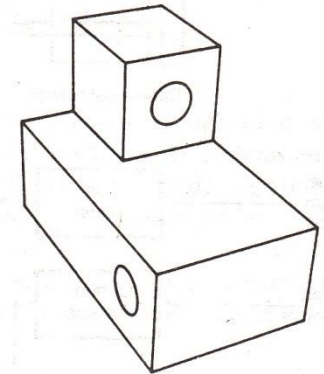
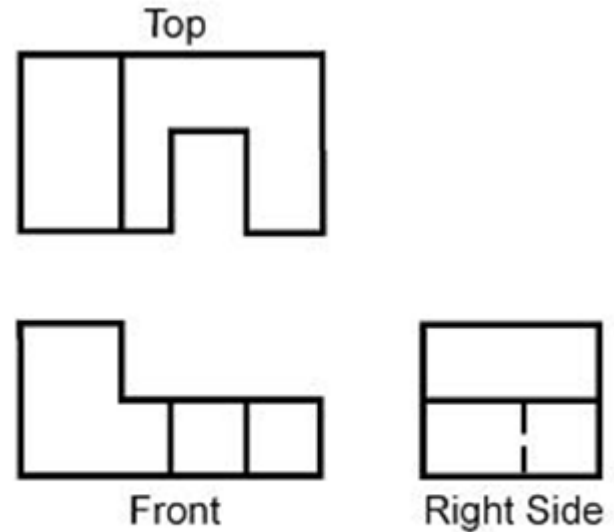
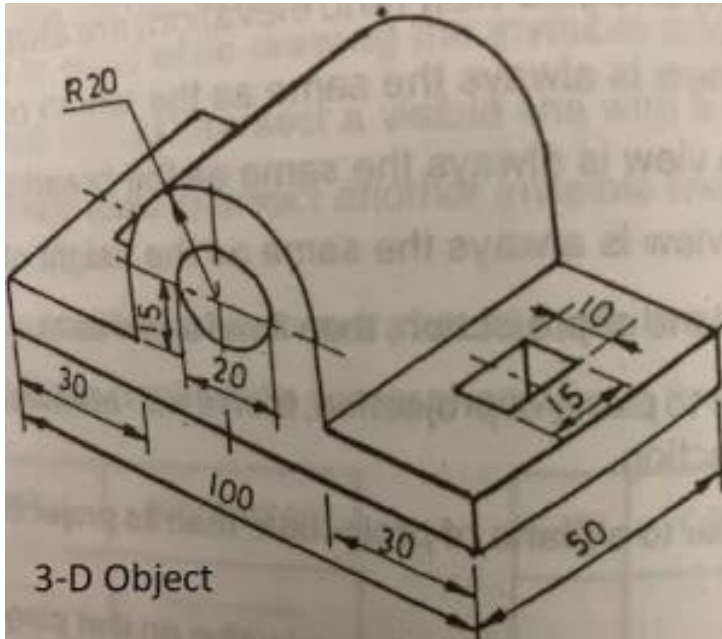


FIGURE 2.3
Perspective
projection of a
simple shape.

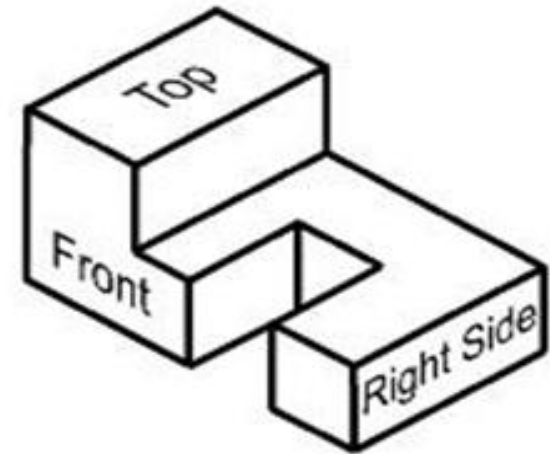
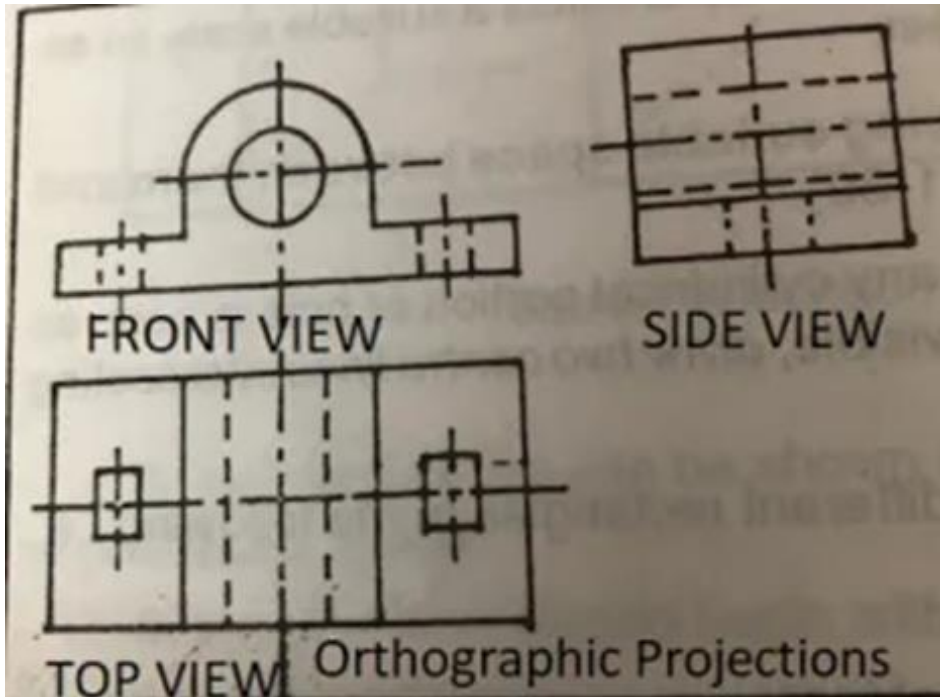


Establishing design representation



2D Orthographic Projection

Establishing design representation



3D Representation

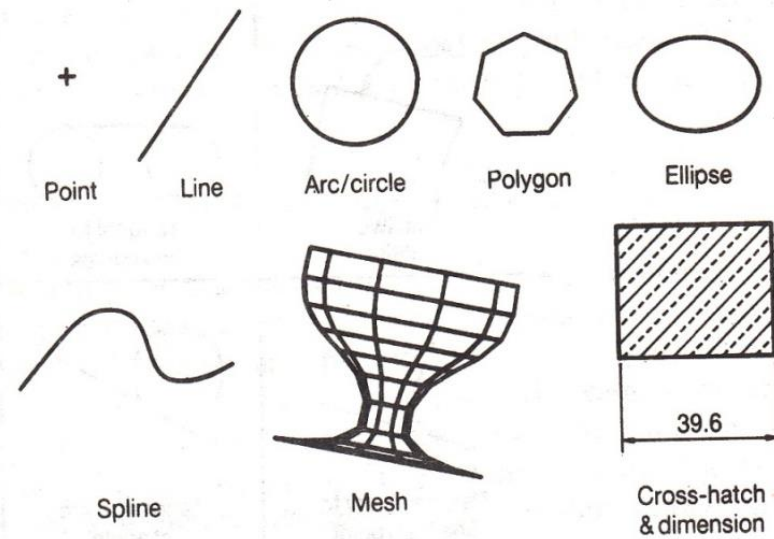
Strength and weakness of Conventional representations



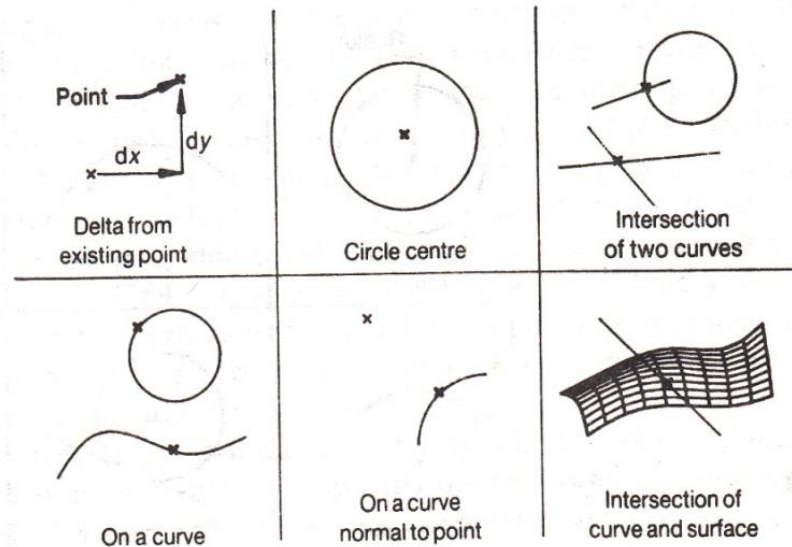
Computer Representation of Drawing

Computer-Aided Draughting

- Entities



- Methods for Point construction



Computer-Aided Draughting

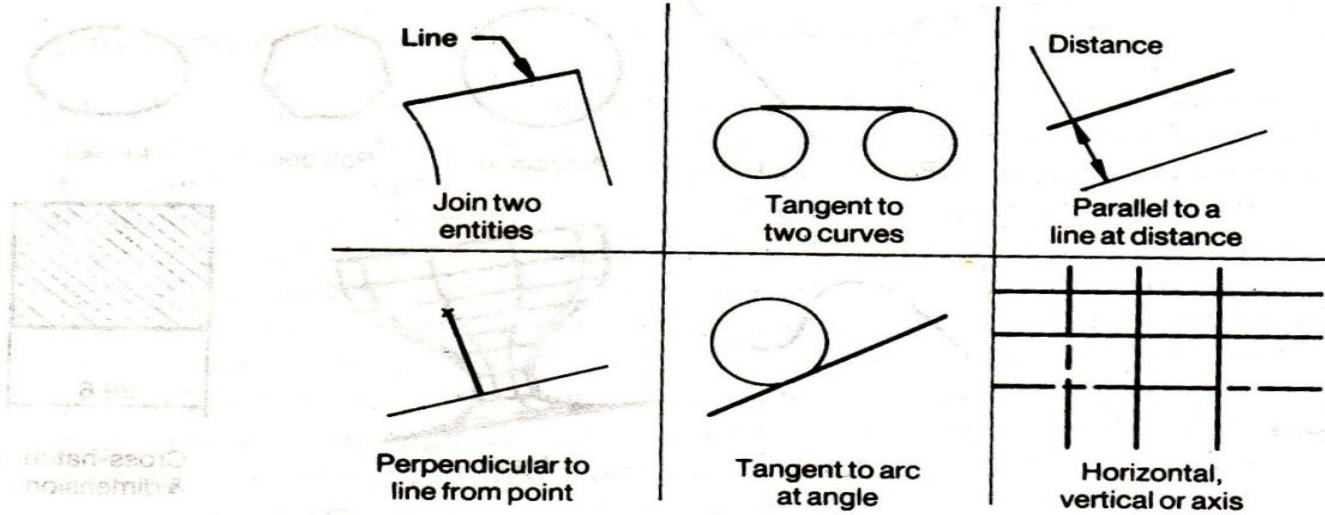


FIGURE 2.9
Methods for line construction.

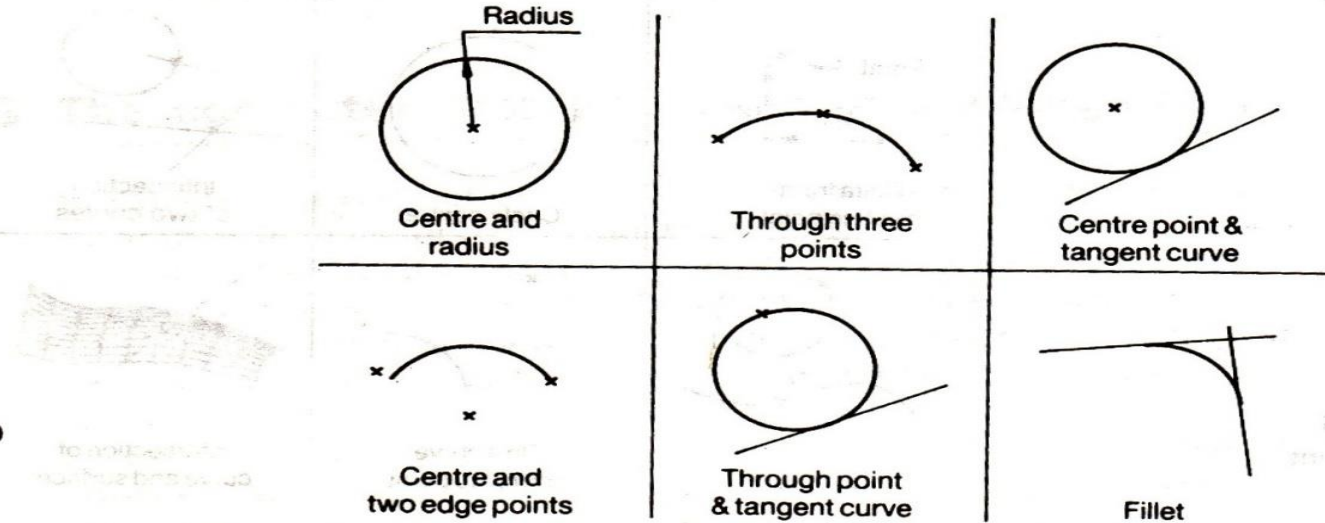


FIGURE 2.10
Methods for arc construction.

3D Modelling Schemes

- Coordinate systems: Cartesian coordinate system, Global coordinate system (GCS), Local coordinate system

34 Defining the model

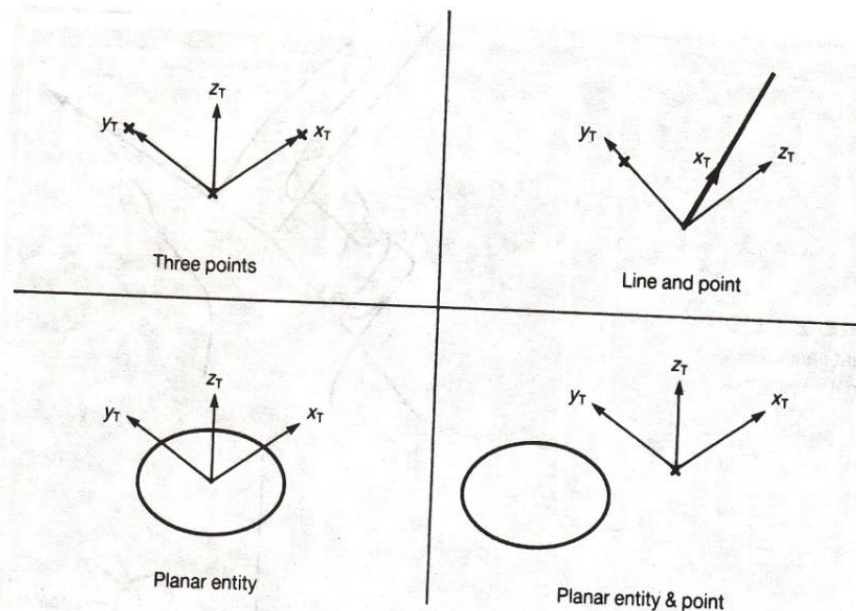


FIGURE 2.14
Methods for defining
local coordinate
systems.

Wire-frame geometry

- Relatively straight forward
- Less computer resource hungry
- Ambiguity in representation
- Deficiency in pictorial representation
- Limited ability to calculate geometric intersections or mechanical properties

FIGURE 2.15
Projected
intersection of
entities.

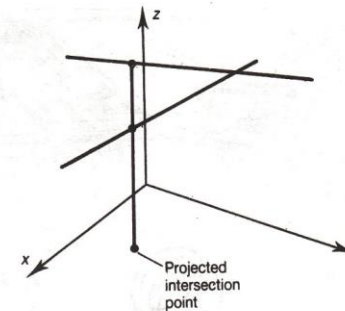
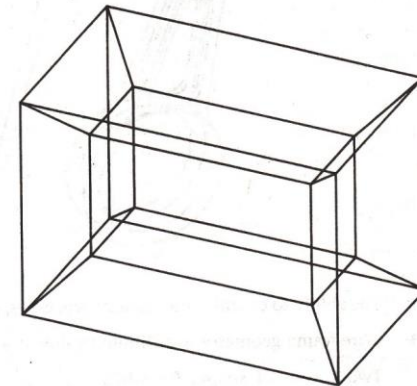


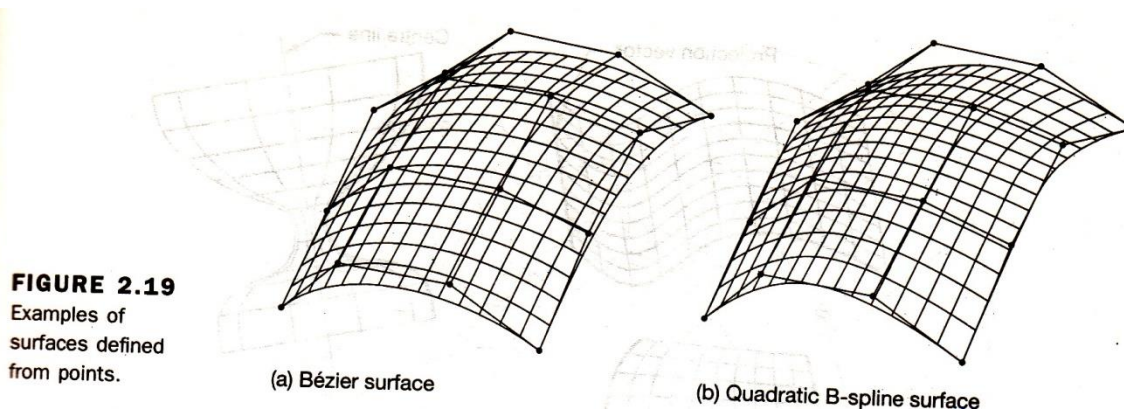
FIGURE 2.16
Ambiguity in wire-
frame models.



Surface representation scheme

- Many ambiguity is are overcome by **Surface modelling** which involves representing the model by specifying some or all of the surfaces of the component.
- Flat surface may be defined by : two parallel lines, through three points or through a line and point.
- Other surface categories :
 - Surfaces are fitted to arrays of data points called control points and the surface is generated either to pass through or to interpolate the points.
 - Surfaces based on curves-the surface may be imagined as forming a skin on top of a wireframe skeleton
 - Surfaces are defined to interpolate between other surfaces

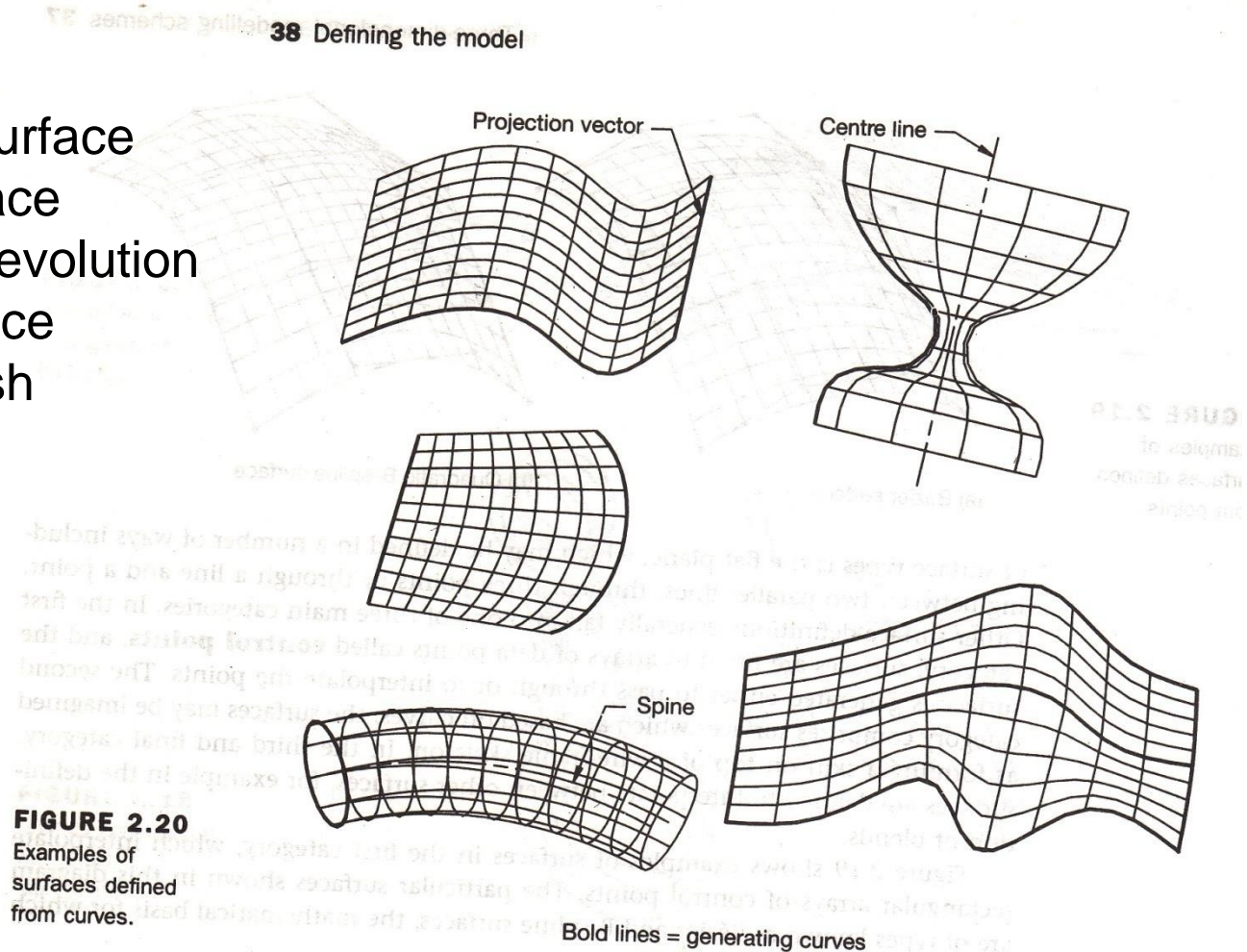
First
category



Surface representation scheme

2nd Category

- Tabulated surface
- Ruled surface
- Surface of revolution
- Swept surface
- Curved mesh



Surface representation scheme

3rd Category

Surfaces are defined to interpolate between other surfaces

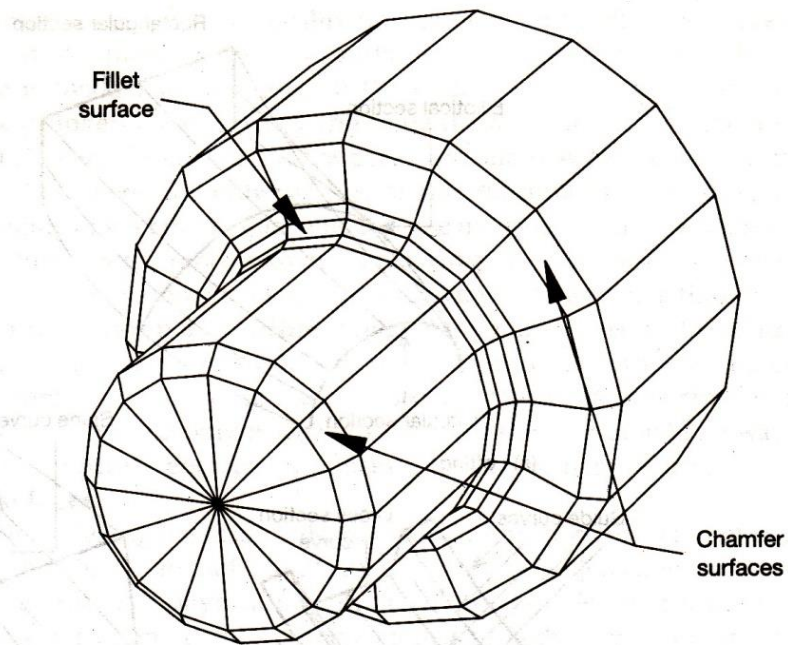


FIGURE 2.21
Examples of
surfaces defined
from other surfaces.

Surface representation scheme

- Surfaces are continuous, with every point on the surface defined by mathematical relationship used in its definition
- In general real artefacts are represented using surface geometry by an assemble of surface patch. A car body may require hundred of patched.

Surface representation scheme

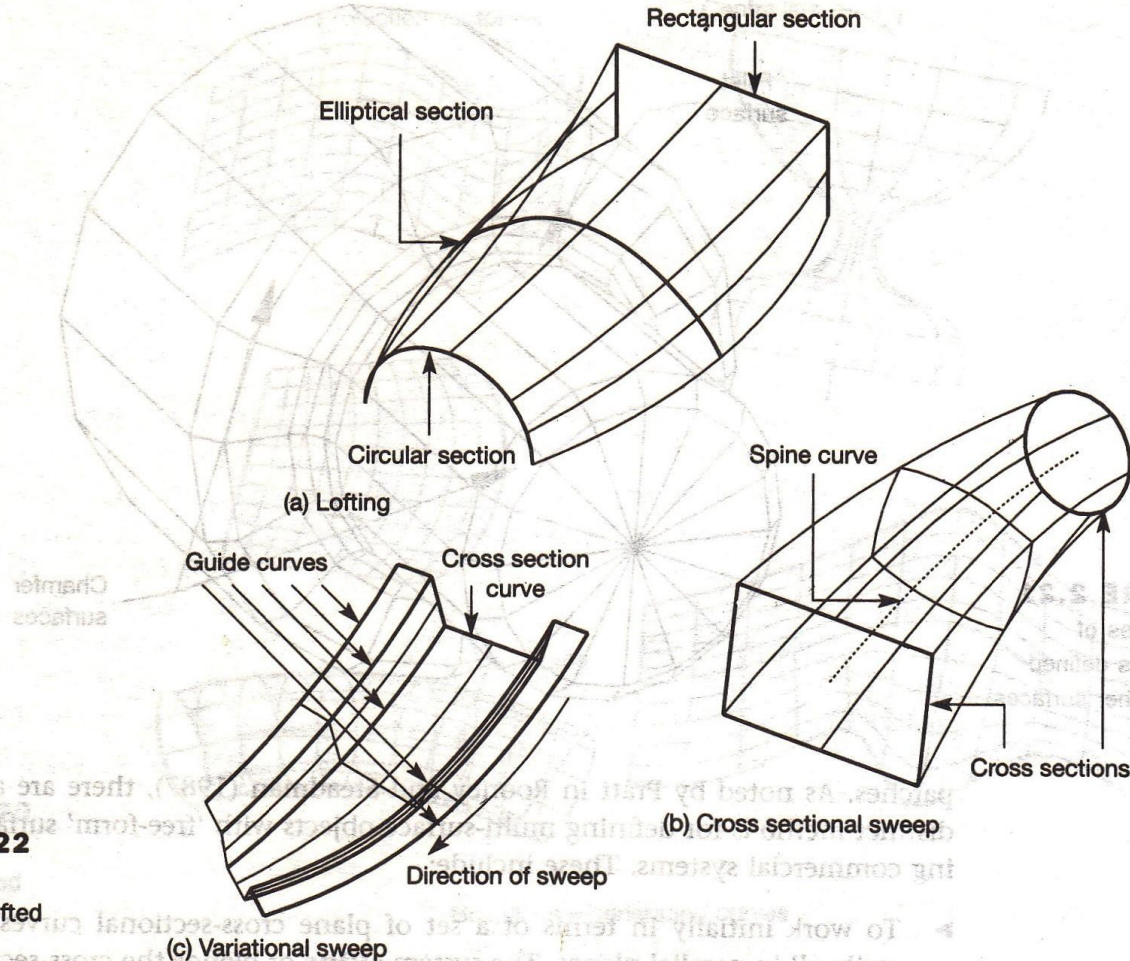
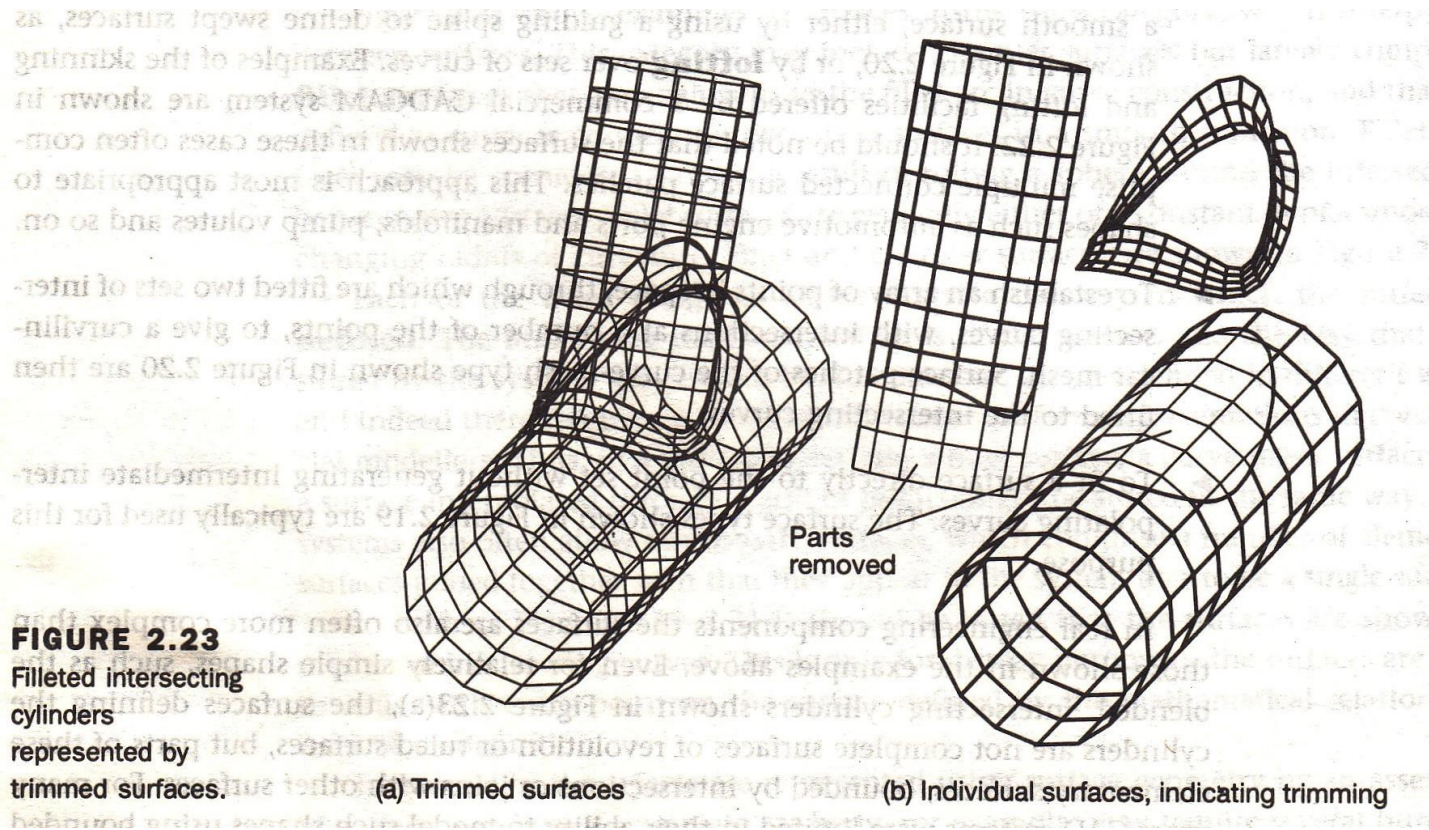


FIGURE 2.22

Examples of skinned and lofted surfaces.

(c) Variational sweep

Surface representation scheme



Applications, +ve, -ve

- Automobile, mould or die manufacture industries
- Shoe and garment industries
- Sheet metal works

- Ambiguity reduced
- Computationally demanding, requires more skills, difficult to interpret complex shapes
- Difficult to represent three or five sided patches

Solid Modelling

- Engineering analysis and generation of manufacturing information requires solid models.
- More complete the representation by Solid models. Smaller the risk of transcription errors
- Conditions for successful representation
 - Complete and unambiguous
 - Appropriate for engineering objects
 - Practical to use with existing computers
- **Two major classes for solid modelling methods**
 - Constructive Solid Geometry (CSG)
 - Boundary Representation (B-Rep)

CSG

- Use simple solid primitives- cuboids, cylinders, spheres, cones etc.
- Use set theory- union, intersection, difference
- Very compact, create solid models unambiguously
- Stored in unevaluated form. Computational issue for edges and surfaces

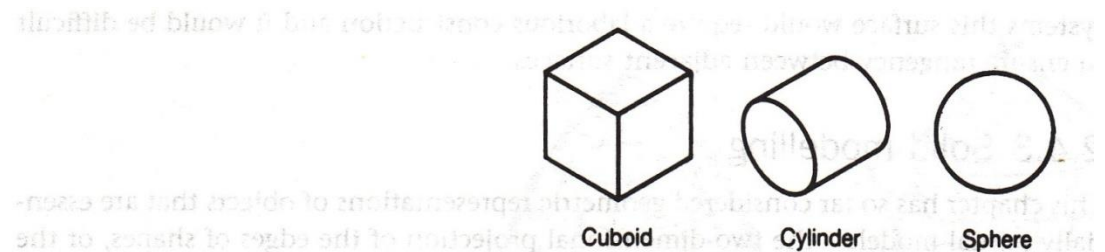


FIGURE 2.26
Primitives offered by a solid modelling system.

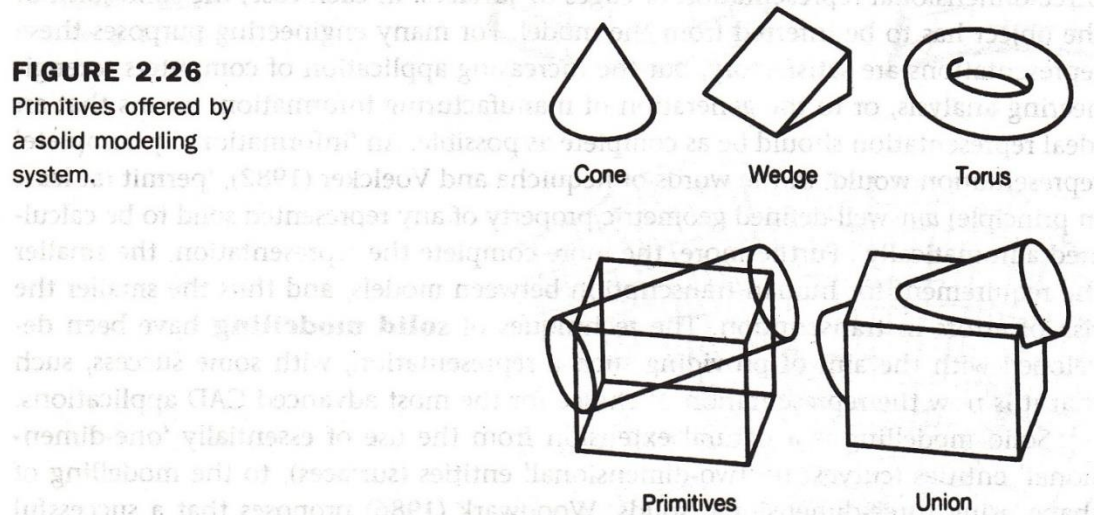
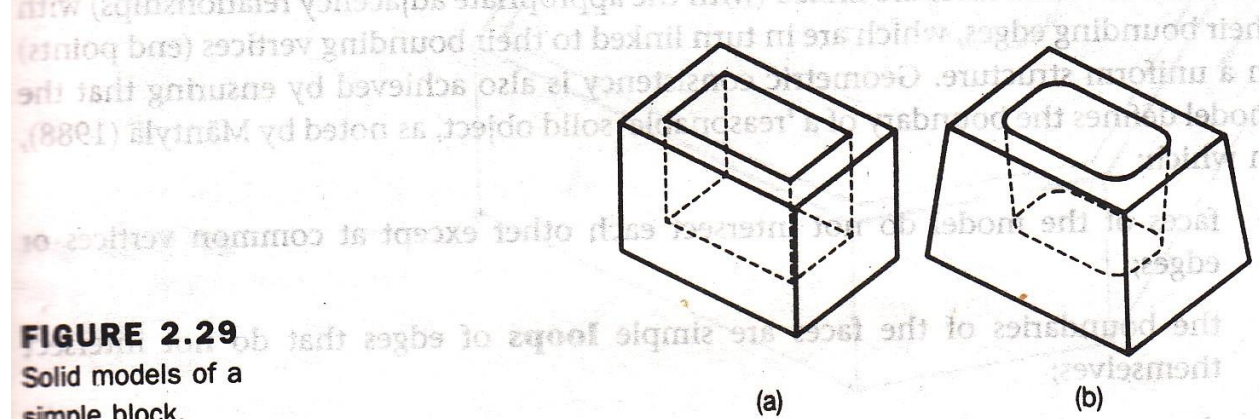
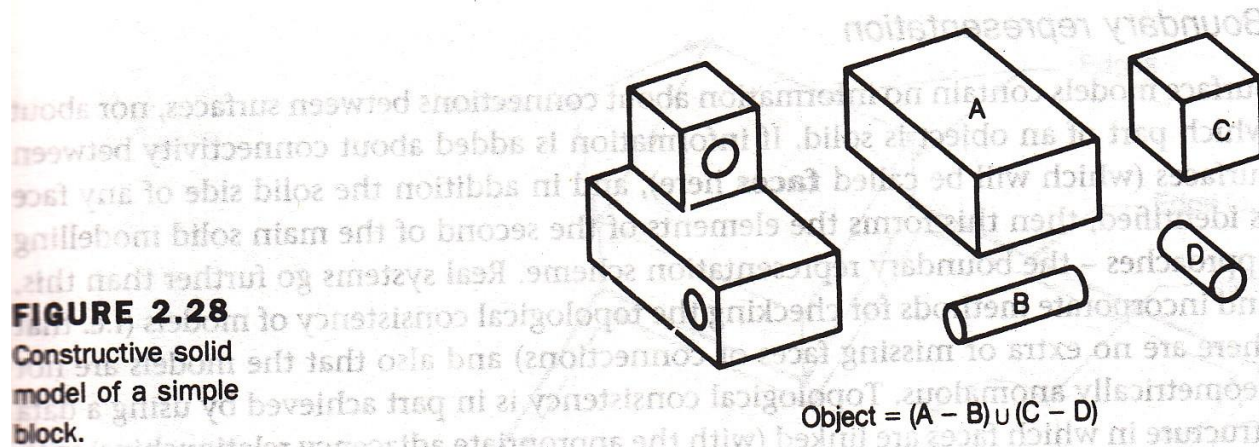


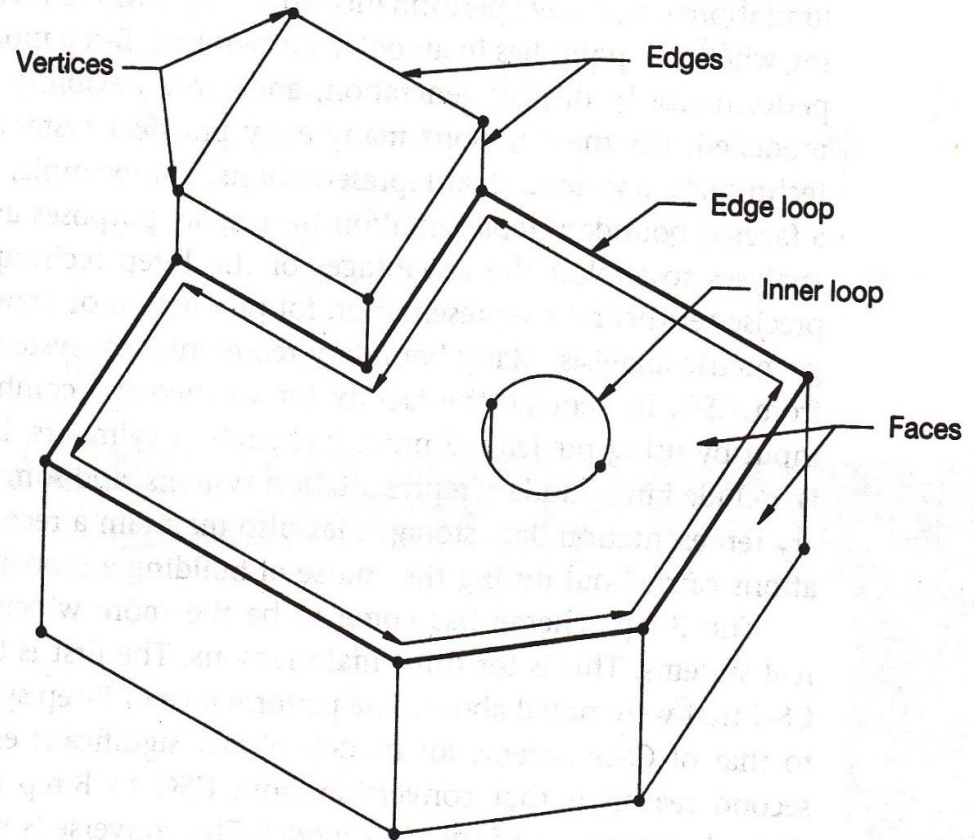
FIGURE 2.27
Boolean operations on a block and cylinder.

CSG



B-Rep

- Topological and Geometric consistency
- Faces of the model do not intersect other except at common vertices and edges
- Boundaries are simple loops of edges
- Set of faces of the model close to form the complete skin of the model with no missing parts



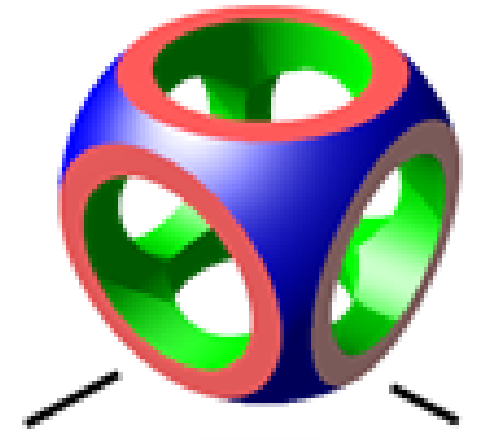
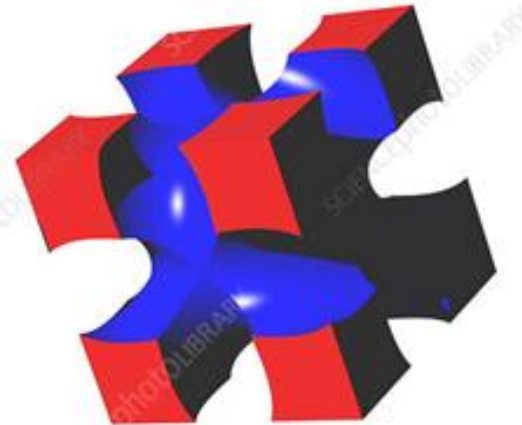
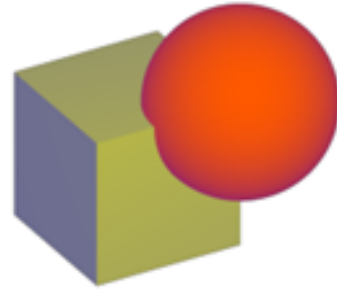
Advantages and Disadvantages of each system

- CSG- Robust and have performance advantages where membership test is required.
- B-rep is better for display generation.

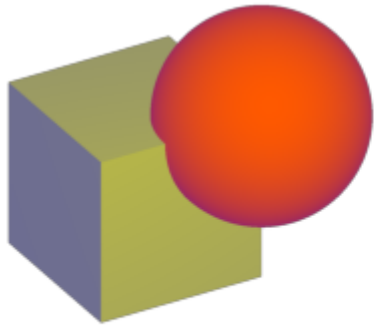
Why B-rep is more popular than CSG?

- First: Geometric limitations of CSG
- Second: Conversion from CSG to B-Rep is easy but B-Rep to CGS is difficult
- Third: Tendency for combining solid modeling with surface modeling and wire frame modeling

Assignment



Boolean Operation Example



Union

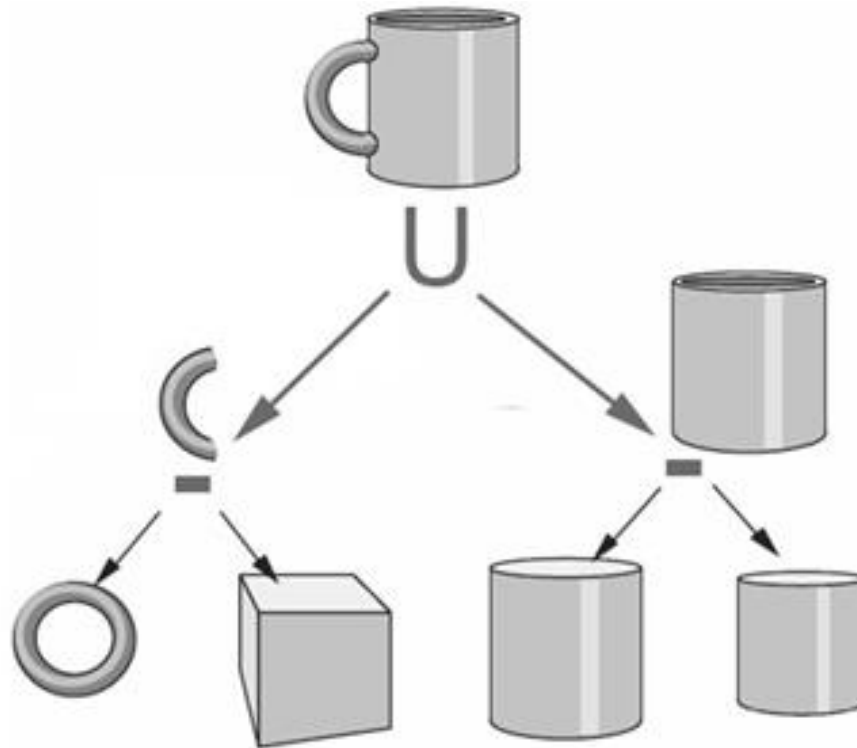


Intersection

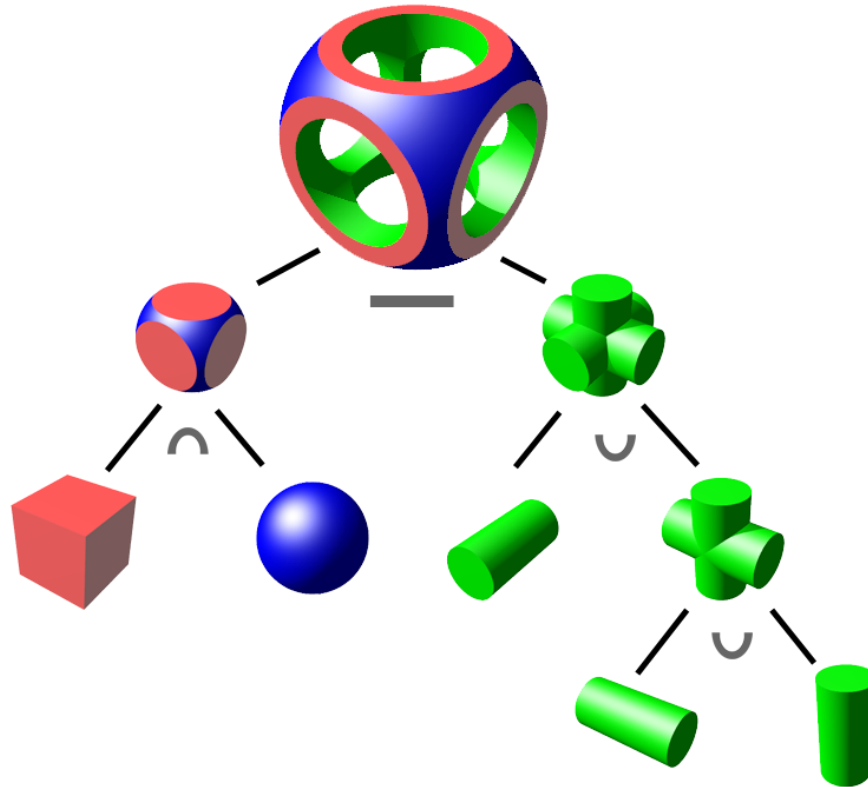


Difference

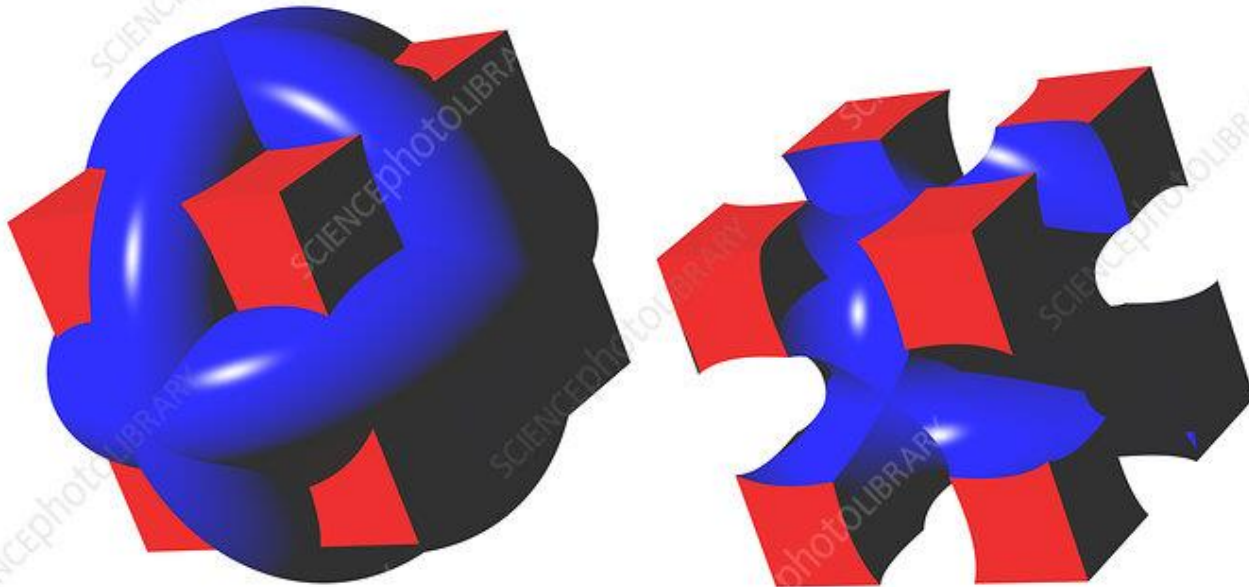
CSG Example



CSG Example



CSG Example



Thank You